

**Advances in Numerical
Solution of
Kinetics Reactions**

MAMS - Technical Report

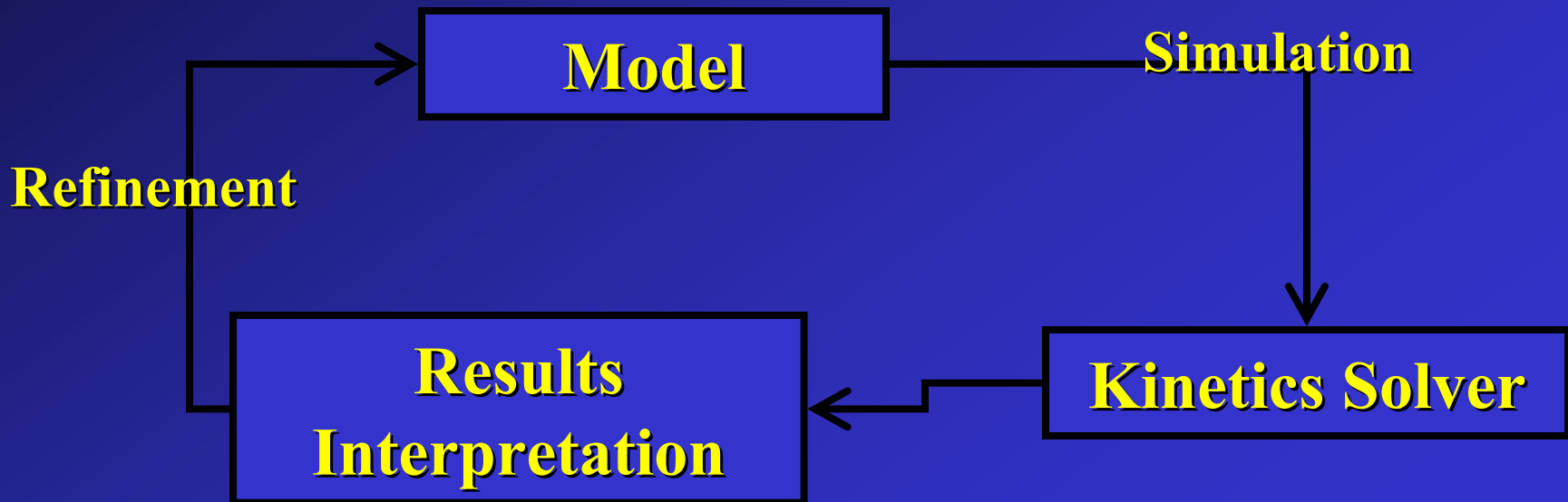
Boanerges Aleman-Meza

Agenda

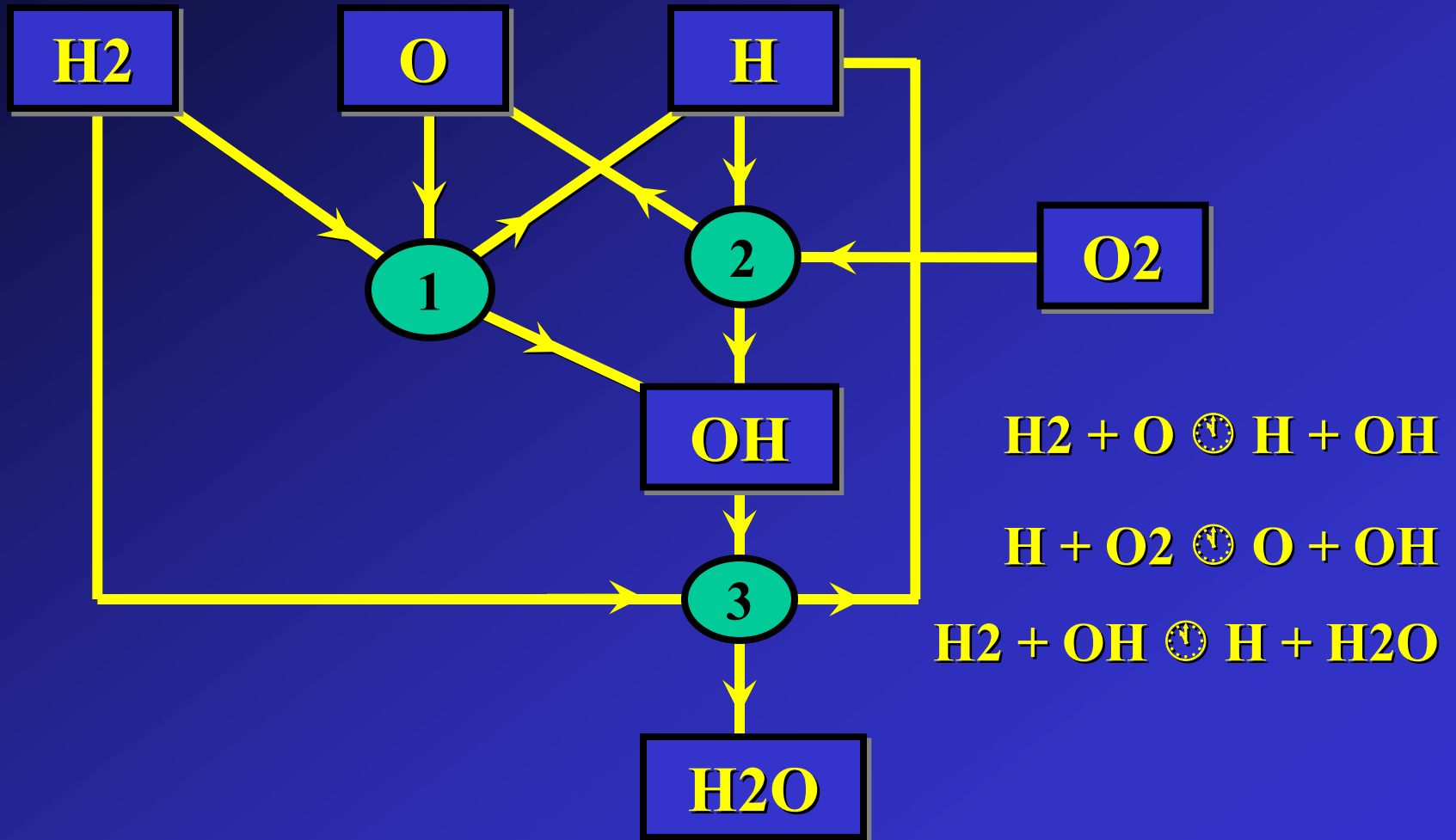
- **Introduction**
- **Numerical Solution**
- **Graphics of the Solution**
- **Conclusions**

Introduction

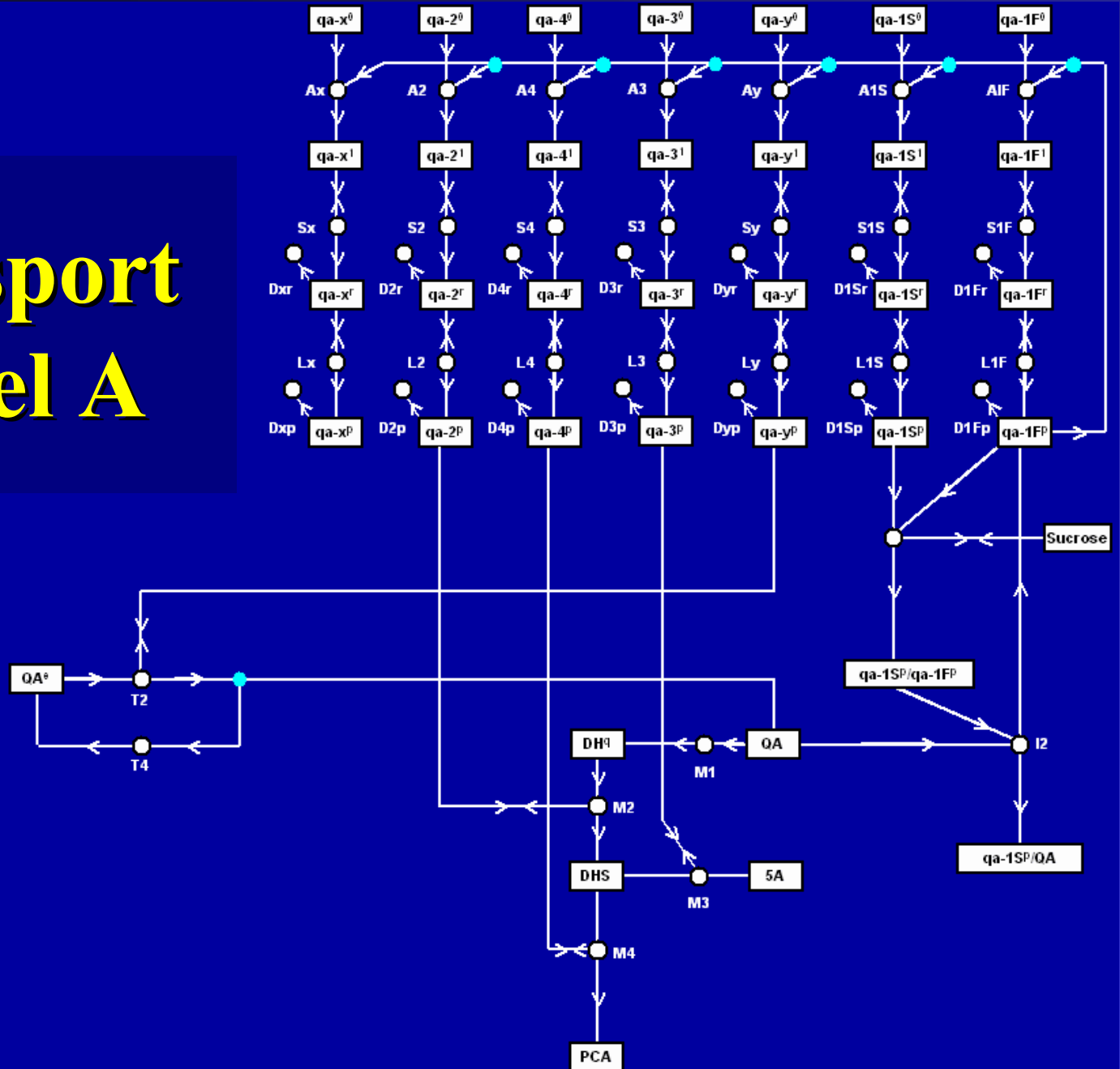
- **Biochemical signaling networks**
- **Model Representation**



Basic Model



Transport Model A

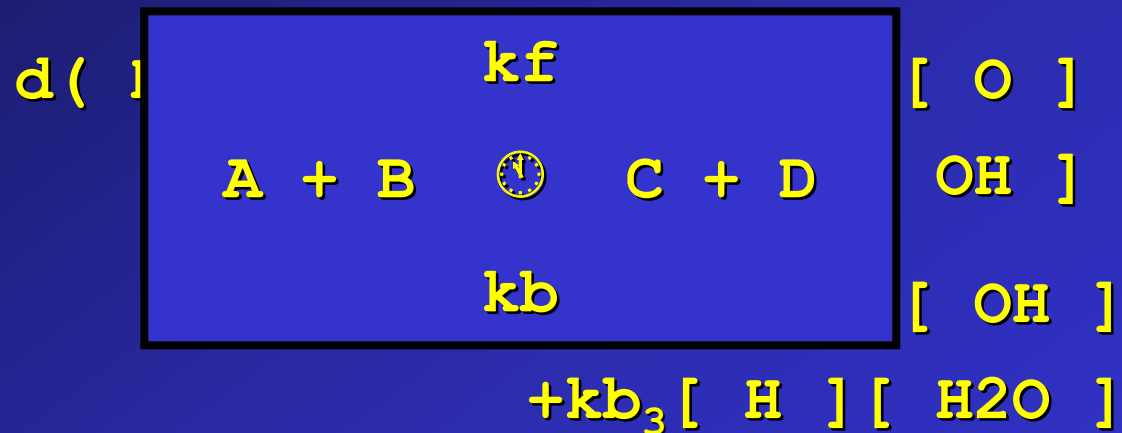


Reactions \rightarrow Equations

- Rate constants

- forward

- backward



Reactions \rightarrow Equations

- Rate constants

- forward

- backward

$$d(O)/dt = -k_f_1 [H_2][O] + k_b_1 [H][OH] + k_f_2 [H][O_2] - k_b_2 [O][OH]$$



Kinetics Solver

- Simulate kinetics reactions like:



- Initial Time \rightarrow Final Time
- Initial Concentrations and rate constants
- Numerical Method selection

Numerical Solution

Numerical Methods

- **Euler Method**

$$y_{n+1} = y_n + h f(t_n, y_n)$$

- **Modified Euler**

$$k_0 = h f(t_n, y_n)$$

$$k_1 = h f(t_n, y_n + k_0)$$

$$y_{n+1} = y_n + \frac{1}{2} (k_0 + k_1)$$

Numerical Methods ...

- **Fourth order Runge-Kutta**

$$k_1 = h f(t_n, y_n)$$

$$k_2 = h f(t_n + \frac{1}{2} h, y_n + \frac{1}{2} k_1)$$

$$k_3 = h f(t_n + \frac{1}{2} h, y_n + \frac{1}{2} k_2)$$

$$k_4 = h f(t_n + h, y_n + k_3)$$

$$y_{n+1} = y_n + (1/6) (k_1 + 2 k_2 + 2 k_3 + k_4)$$

Numerical Methods ...

- **Adaptive Runge-Kutta Fehlberg**

$$k_1 = h f(t_n, y_n)$$

$$k_2 = h f(t_n + \frac{1}{4} h, y_n + \frac{1}{4} k_1)$$

$$k_3 = h f(t_n + c_1 h, y_n + c_2 k_1 + c_3 k_2)$$

$$k_4 = h f(t_n + c_4 h, y_n + c_5 k_1 + c_6 k_2 + c_7 k_3)$$

$$k_5 = h f(t_n + h, y_n + c_8 k_1 + c_9 k_2 + c_{10} k_3 + c_{11} k_4)$$

$$k_6 = h f(t_n + \frac{1}{2} h, y_n + c_{12} k_1 + 2 k_2 + c_{13} k_3 + c_{12} k_4 + c_{13} k_5)$$

4th

$$y_{n+1} = y_n + c_{14} k_1 + c_{15} k_2 + c_{16} k_3 + c_{17} k_4$$

5th

$$y_{n+1} = y_n + c_{18} k_1 + c_{19} k_3 + c_{20} k_5 + c_{21} k_6$$

Numerical Methods ...

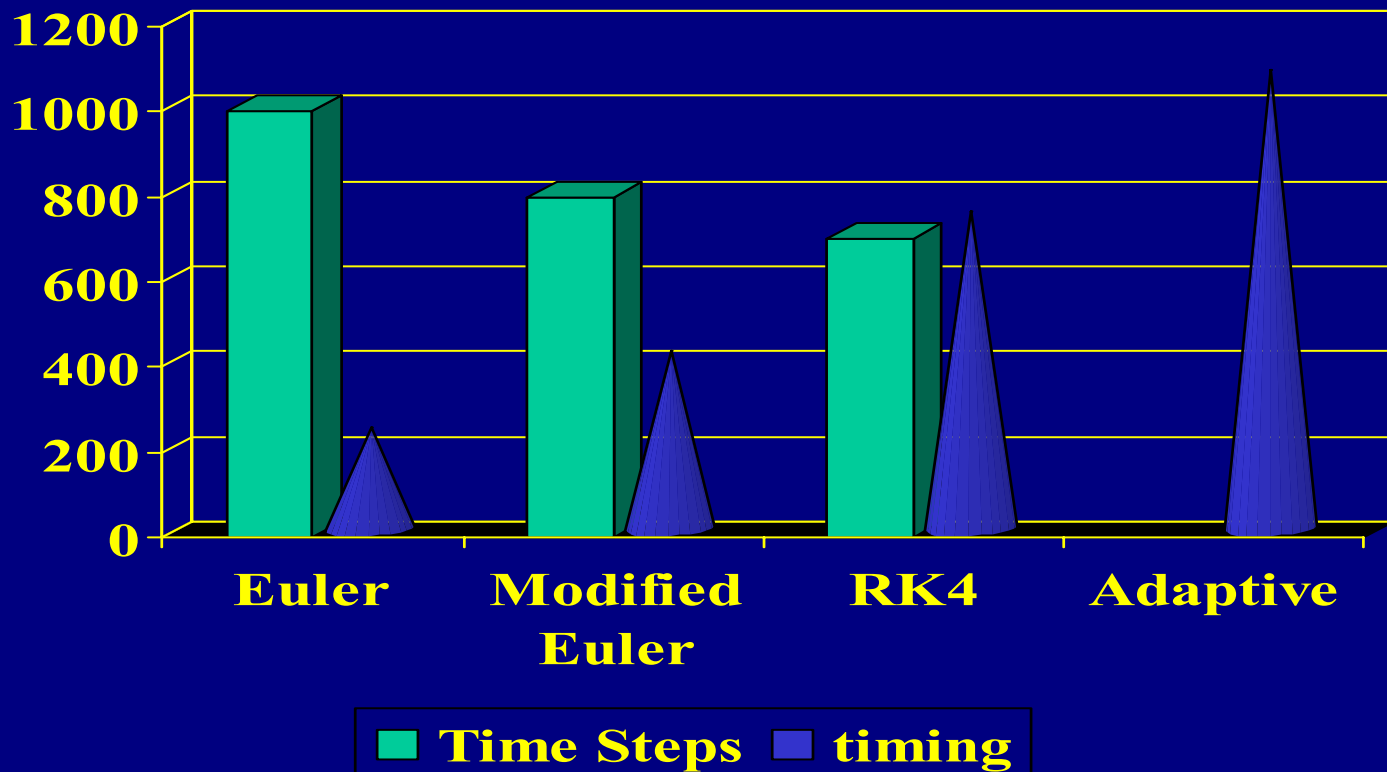
- **Backward Difference Formula (Implicit)**

$$y_{n+1} = (4/3) y_n - (1/3) y_{n-1} + (2/3) y'_{n+1}$$

- **Jacobian evaluation**
- **System of Equations: $O(m^3) + O(m^2)$**

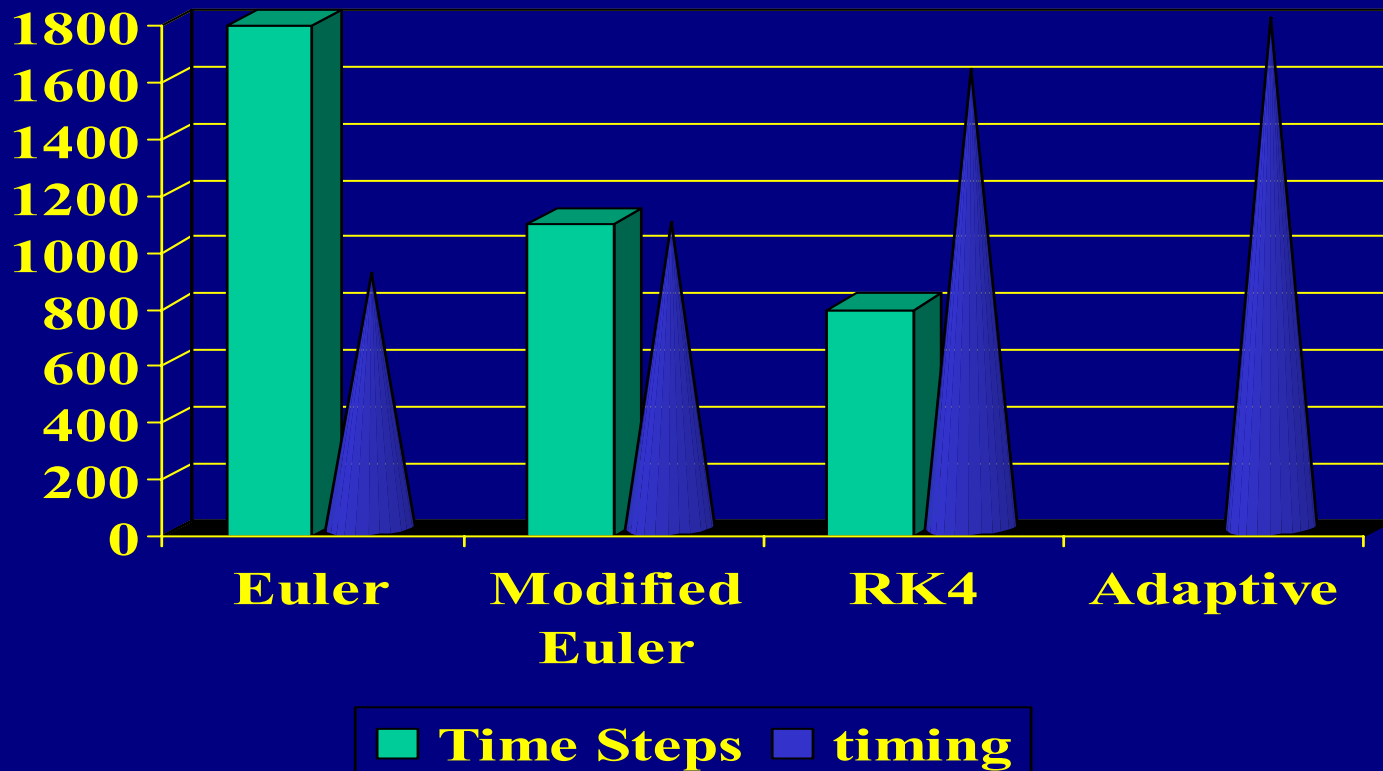
Performance

- With data set QA-Tr.B



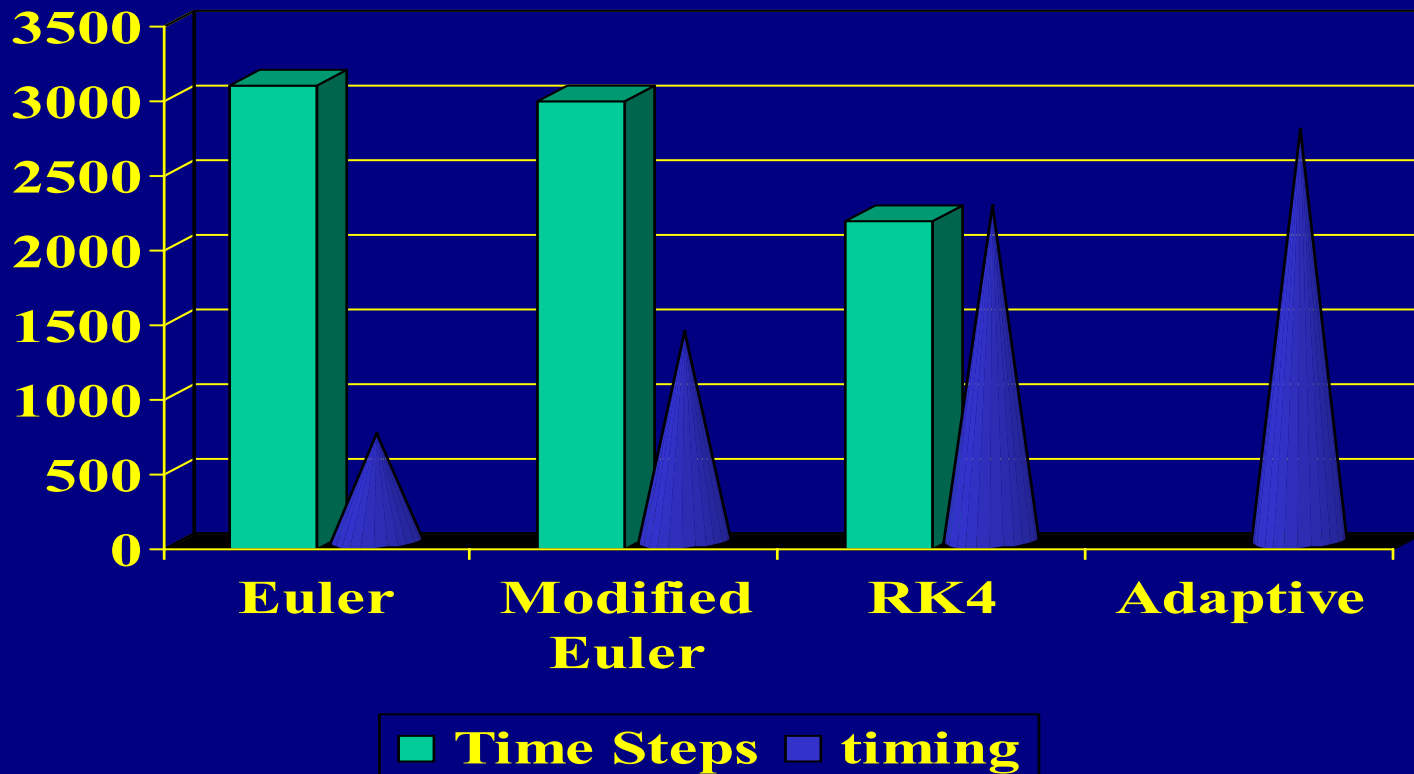
Performance

- With data set QA-A



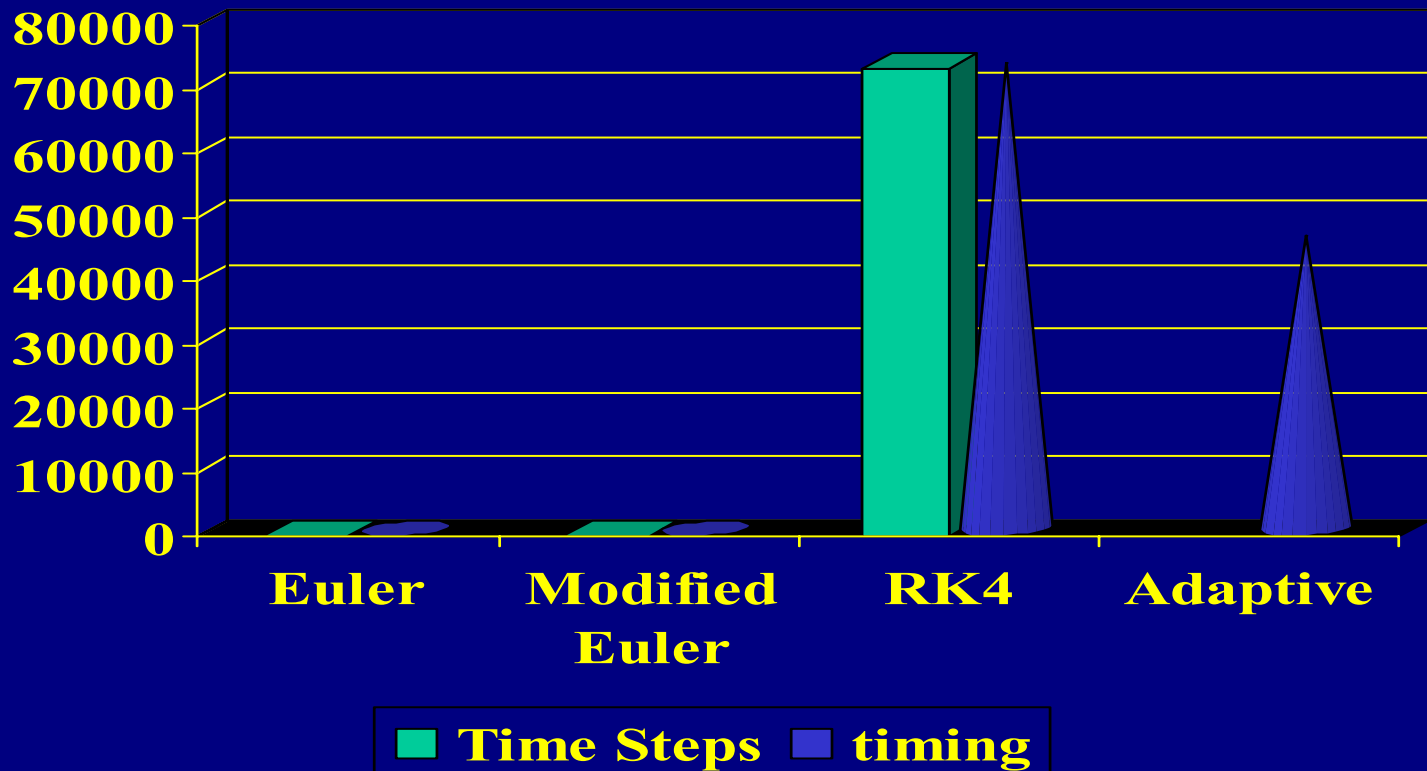
Performance

- With data set QA-Tr.-A



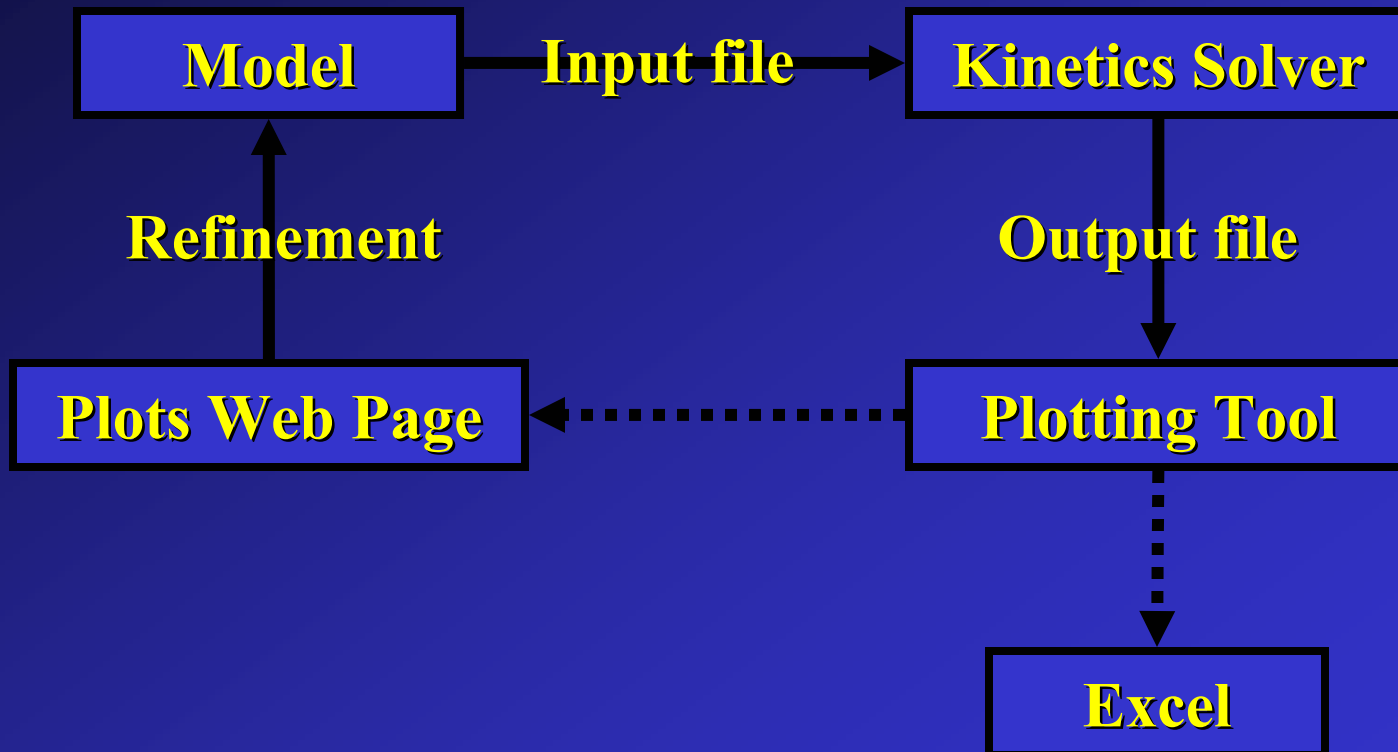
Performance

- With data set LAC-PTS

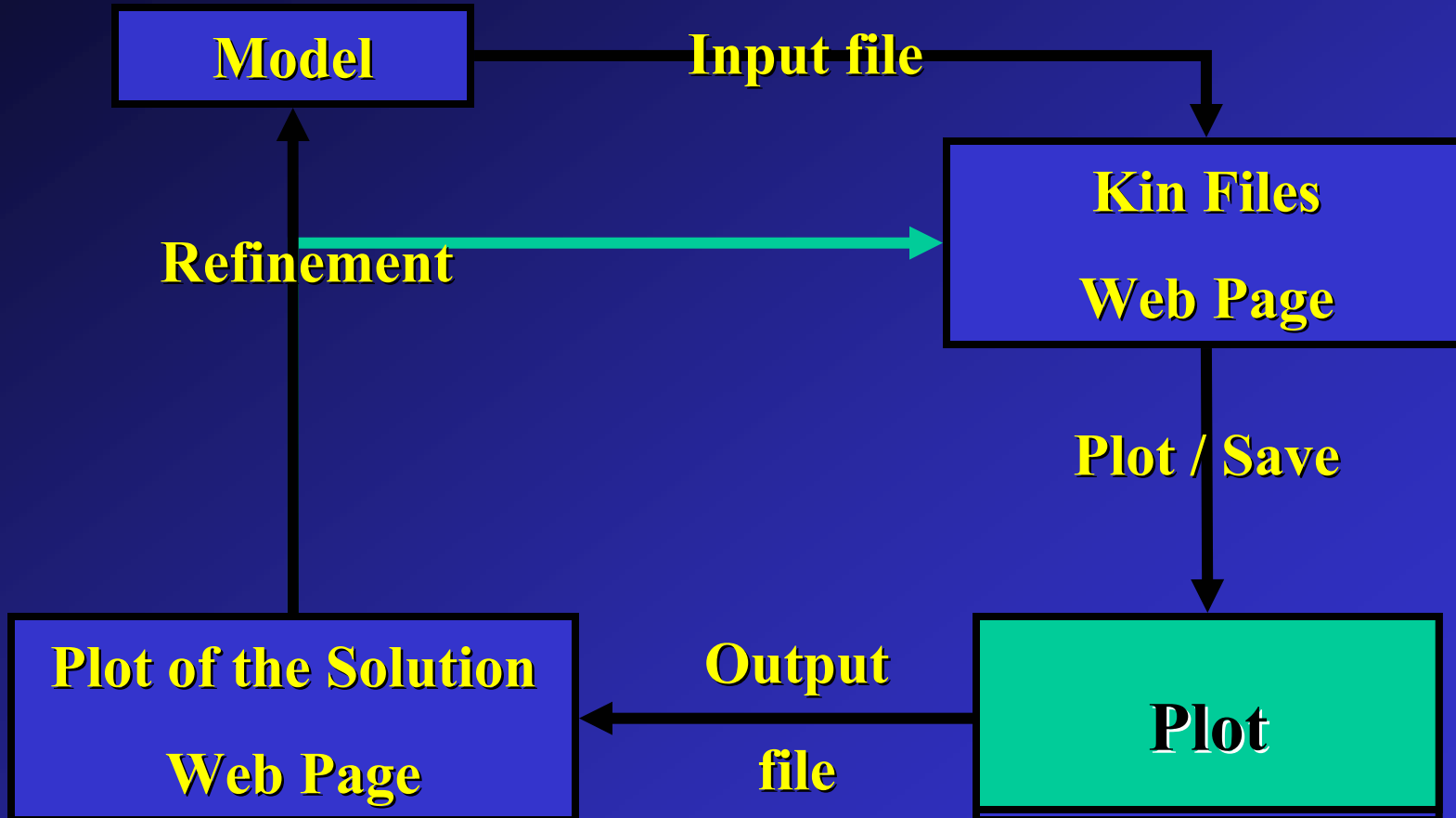


Graphics of the Solution

Using the Kinetics Solver



Using the Kinetics Solver ...



Conclusions

Conclusions

- **Numerical methods :**
 - performance vs. accuracy
 - data set parameters
 - **Stiff solver inadequate**
- **Plotting by Web Page**
- **“Computing Life”**

Questions and Comments!